

Concentrated beams in differentially rotating and stratified fluids and their reflection at a turning point

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(Received 6 January 2026)

Concentrated wave beams are analysed both theoretically and numerically in a general rotating and stratified axisymmetric medium, where both the rotation rate and the Brunt-Väisälä frequency vary with position. The fluid is assumed to be incompressible, weakly diffusive, and weakly viscous. The analysis is conducted within the Boussinesq approximation and a linear framework, with a prescribed frequency. An asymptotic solution is derived in the limit of weak viscosity and diffusivity, describing a harmonic beam of inertia gravity waves localized around a characteristic (or ray path), similar to those generated by boundary singularities or critical points. This solution is shown to break down when the characteristic reaches a turning point which corresponds to the transition from oscillatory to evanescent behaviour. A local asymptotic analysis near the turning point demonstrates that the wave beam reflects, preserving its transverse structure while acquiring a phase shift of $\pm\pi/2$. These theoretical predictions are validated through numerical simulations, which show that the wave beam structure, both near and far from the turning point, is accurately reproduced.

1. Introduction

Waves are ubiquitous in rotating and stratified fluids. They play a key role in the dynamics of both the ocean (Munk & Wunsch, 1998) and the atmosphere (Fritts & Alexander, 2003). In the ocean, such waves can be generated by tidal flows interacting with topography (Wunsch, 1975). When the topography is supercritical, that is, when it has a slope tangent to the direction of wave propagation, concentrated wave beams are emitted from so-called critical (slope) points. These beams have been studied both experimentally (Zhang *et al.*, 2007; King *et al.*, 2009; Echeverri & Peacock, 2010) and theoretically (St Laurent *et al.*, 2003; Llewellyn Smith & Young, 2003; Balmforth & Peacock, 2009) in this context. Similar concentrated beams also occur in rotating fluids (Greenspan, 1968). They have often been investigated in spherical geometries (Calkins *et al.*, 2010; Koch *et al.*, 2013; Cébron *et al.*, 2019; Lin & Noir, 2021; He *et al.*, 2022, 2023) due to their relevance in planetary and stellar interiors (Le Bars *et al.*, 2015). Their structure has been examined theoretically in works such as Walton (1975); Kerswell (1995); Tilgner (2000), and more recently in Le Dizès & Le Bars (2017).

The theoretical description of these beams is based on the similarity solutions obtained by Moore & Saffman (1969) for rotating fluids and Thomas & Stevenson (1972) for stratified fluids. These asymptotic viscous solutions have primarily been used to describe wave fields far from a localised oscillating source (Hurley & Keady, 1997; Voisin, 2003; Cortet *et al.*, 2010; Machicoane *et al.*, 2015). They are parametrised by an index m ,

which characterises the strength of the underlying inviscid singularity. Only recently have these solutions been applied to describe concentrated beams issued from critical points (Le Dizès & Le Bars, 2017; He *et al.*, 2022, 2023; Le Dizès, 2024). Furthermore, Ogilvie (2005) and He *et al.* (2023) have shown that these solutions can also describe the asymptotic viscous structure of the internal shear layers associated with wave attractors.

Most of the existing studies have focused on uniformly rotating and stratified fluids. In a non-uniform medium, the direction of wave propagation is expected to vary with position. In such cases, a local wave analysis is typically employed, based on WKB approximations and ray tracing techniques (Lighthill, 1978; Marks & Eckermann, 1995; Prat *et al.*, 2016; Broutman *et al.*, 2004; Prat *et al.*, 2018). Rays may, in particular, encounter points where they can no longer propagate. At these so-called turning points, the rays reflect and form a typical cusp structure (Friedlander & Siegmund, 1982). The wave solution near turning points is expected to be described by an Airy equation (Wasow, 1985; Sutherland, 2010). The local wave approach has helped explain various features observed in the structure of free oscillating modes in closed geometries (Dintrans *et al.*, 1999; Maas, 2001; Harlander & Maas, 2007; Mathis, 2009; Baruteau & Rieutord, 2013; Guenel *et al.*, 2016; Mirouh *et al.*, 2016; Astoul *et al.*, 2021).

The concentrated beams generated from critical or singular points are small-scale structures, for which this local wave approach is expected to be applicable. We will show that the similarity solution of Moore & Saffman (1969) remains valid in a non-uniform medium, provided the beam width is small compared to the spatial scale associated with the varying background. The same conclusion was reached by Kistovich & Chashechkin (1998) for non-rotating fluids. The beam's width and amplitude vary according to the local properties of the medium. We will demonstrate that the similarity solution breaks down at the turning point. A new local solution will be constructed to describe the beam behaviour near this point, showing that the beam reflects while maintaining its similarity structure and acquiring a phase shift of $\pm\pi/2$, as for non-rotating fluids (Kistovich & Chashechkin, 1998). These theoretical predictions are validated using numerical simulations of the linear governing equations.

The paper is organised as follows. Section §2 presents the general framework. We consider a non-uniform axisymmetric medium in which the angular velocity varies with the cylindrical radius and the Brunt-Väisälä frequency varies with the spherical radius. The governing equations, ray equations, and local dispersion relations are provided in this section. We also derive the form of the governing equations in the local Frenet-Serret frame attached to a given characteristic. Section §3 uses these equations to obtain an asymptotic solution describing viscous wave beams concentrated along a characteristic. The classical similarity solution of Moore & Saffman (1969) is recovered as one possible solution. Section §4 analyses the behaviour of the viscous solution near a turning point. The appropriate scalings, the local governing equation, and its solution are derived. Section §5 presents the numerical validation of the theory. Simulations are conducted in a finite domain with a non-stratified configuration, using a localised forcing to generate the concentrated beam and sponge layers to prevent boundary reflections. The structure of the solution, both near and far from the turning point, is compared with the theoretical predictions. Finally, in the conclusion, we summarise the results and discuss their possible extension to finite geometries.

2. Framework

We consider an incompressible fluid undergoing differential rotation about the vertical axis Oz , with an angular velocity $\Omega(r)$ that depends only on the cylindrical radial

coordinate r . The fluid is also assumed to be stably stratified in a central gravitational field, with a Brunt-Väisälä frequency $N(\rho)$ that depends solely on the spherical radial coordinate ρ . The kinematic viscosity ν and the scalar diffusivity α are both taken to be constant. The model chosen for the stratification and angular rotation mimics configurations that can be found in stellar interiors (e.g. Dintrans *et al.*, 1999). It can be rigorously justified provided that the centrifugal force remains negligible compared to gravity. However, this is not our purpose here, as other models can be adapted to the following derivation without difficulty.

We are interested in harmonic, axisymmetric perturbations of frequency ϖ ($\varpi > 0$). These perturbations are described by the velocity \mathbf{U} , pressure P and buoyancy B , which are expressed in the form:

$$(\mathbf{U}, P, B) = (\mathbf{u}, p, b)e^{-i\varpi t} + c.c. \quad (2.1)$$

where “c.c.” denotes the complex conjugate. The governing equations for the amplitudes \mathbf{u} , p and b are derived from the Boussinesq approximation of the Navier-Stokes equations. After non-dimensionalizing all quantities using a characteristic length scale L and a characteristic velocity scale V , the linearised equations take the form:

$$-i\varpi\mathbf{u} + 2\Omega(\hat{\mathbf{e}}_z \times \mathbf{u}) + r(\mathbf{u} \cdot \nabla\Omega)\hat{\mathbf{e}}_\phi = -\nabla p + b\hat{\mathbf{e}}_\rho + E\nabla^2\mathbf{u}, \quad (2.2a)$$

$$\nabla \cdot \mathbf{u} = 0, \quad (2.2b)$$

$$-i\varpi b + N^2\mathbf{u} \cdot \hat{\mathbf{e}}_\rho = (E/Pr)\nabla^2 b, \quad (2.2c)$$

where $Pr = \nu/\alpha$ is the Prandtl number and $E = \nu/(VL)$ the Ekman number. In these equations, Ω and N now denote the rotation rate and the Brunt-Väisälä frequency non-dimensionalized by V/L . In the following, we assume $E \ll 1$ and $Pr \geq O(1)$. The cylindrical and spherical vector bases are denoted by $(\hat{\mathbf{e}}_r, \hat{\mathbf{e}}_\phi, \hat{\mathbf{e}}_z)$ and $(\hat{\mathbf{e}}_\rho, \hat{\mathbf{e}}_\theta, \hat{\mathbf{e}}_\phi)$, respectively.

2.1. Characteristics and local dispersion relation of the non-dissipative problem

In the non-dissipative limit ($\nu = \alpha = 0$), the system (2.2) can be reduced to a single second-order equation for the pressure p (see, for instance, Friedlander & Siegmann, 1982; Mirouh *et al.*, 2016). Retaining only second-order derivatives, this equation takes the form:

$$(\varpi^2 - N^2 \sin^2 \theta) \frac{\partial^2 p}{\partial r^2} + 2N^2 \cos \theta \sin \theta \frac{\partial^2 p}{\partial z \partial r} + (\varpi^2 - N^2 \cos^2 \theta - \xi^2) \frac{\partial^2 p}{\partial z^2} = 0, \quad (2.3)$$

where ξ is the epicyclic frequency, defined by

$$\xi^2(r) = 2\Omega(r)\omega(r), \quad (2.4)$$

and $\omega(r) = (1/r)\partial_r(r^2\Omega)$ is the background vorticity. Equation (2.3) is a generalization of the classical Poincaré equation, extended to account for both differential rotation and radial stratification. In the case of solid-body rotation and uniform stratification, it reduces to the standard form with $\xi^2 = 4\Omega^2$.

This equation can also be derived from the full system (2.2) in the inviscid and non-diffusive limit ($\nu = \alpha = 0$) by assuming a local plane-wave solution of the form $\exp(ik_r r + ik_z z)$ with $k_r \gg 1$ and $k_z \gg 1$. This leads to the local dispersion relation for inertia-gravity waves:

$$\varpi^2 = N^2 \frac{(k_z \cos \theta - k_r \sin \theta)^2}{k^2} + \xi^2 \frac{k_z^2}{k^2}, \quad k^2 = k_r^2 + k_z^2, \quad (2.5)$$

which corresponds to (2.3) under the substitution ∂_r by ik_r and ∂_z by ik_z . We assume a

stable configuration in which both N^2 and ξ^2 are positive. Equation (2.5) determines the allowable range of wave frequencies. At the equator ($\theta = 0$), the frequency ranges from 0 to $\sqrt{N^2 + \xi^2}$, while at the poles ($\theta = \pm\pi/2$), it ranges from $\min(N, \xi)$ to $\max(N, \xi)$, depending on the relative magnitudes of N to ξ . From the dispersion relation (2.5), we can define both the phase velocity and group velocity. The phase velocity is given by

$$\mathbf{v}^{(\varphi)} = (v_r^{(\varphi)}, v_z^{(\varphi)}) = \left(\frac{\varpi k_r}{k^2}, \frac{\varpi k_z}{k^2} \right),$$

while the group velocity is

$$\mathbf{v}^{(g)} = (v_r^{(g)}, v_z^{(g)}) = \left(\frac{\partial \varpi}{\partial k_r}, \frac{\partial \varpi}{\partial k_z} \right) \quad (2.6)$$

with explicit expressions:

$$v_r^{(g)} = -k_z \frac{N^2 k_\rho k_\theta + \xi^2 k_r k_z}{\varpi}, \quad v_z^{(g)} = k_r \frac{N^2 k_\rho k_\theta + \xi^2 k_r k_z}{\varpi}, \quad (2.7)$$

where

$$k_\rho = k_r \cos \theta + k_z \sin \theta, \quad k_\theta = -k_r \sin \theta + k_z \cos \theta.$$

The paths of characteristics associated with equation (2.3) are given by

$$\frac{dz}{dr} = \frac{N^2 \sin \theta \cos \theta \pm \sqrt{\Delta}}{\varpi^2 - N^2 \sin^2 \theta}, \quad (2.8a)$$

$$\frac{dr}{dz} = \frac{N^2 \sin \theta \cos \theta \mp \sqrt{\Delta}}{\varpi^2 - N^2 \cos^2 \theta - \xi^2}, \quad (2.8b)$$

where

$$\Delta = \varpi^2(N^2 + \xi^2 - \varpi^2) - N^2 \xi^2 \sin^2 \theta. \quad (2.9)$$

The curves defined by the vanishing of Δ correspond to turning points, which play a key role in the wave dynamics. As explained in Friedlander & Siegmund (1982), these curves separate regions where equation (2.3) is hyperbolic ($\Delta > 0$) from those where it is elliptic ($\Delta < 0$). Only the hyperbolic regions ($\Delta \geq 0$) are relevant for wave propagation, as they admit characteristic paths. In a non-stratified fluid ($N = 0$), turning points occur at cylindrical locations where $\varpi = \xi(r)$. At these points, the ray path becomes horizontal. Conversely, in a non-rotating fluid ($\Omega = 0$) or in a irrotational flow ($\omega = 0$), the turning points lie at the spherical locations where $\varpi = N(\rho)$. At these points, the ray path becomes radial.

Moreover, the slope of the characteristic can be related to the group velocity. From equation (2.10), we have:

$$\frac{v_z^{(g)}}{v_r^{(g)}} = -\frac{k_r}{k_z} = \frac{N^2 \sin \theta \cos \theta \pm \sqrt{\Delta}}{\varpi^2 - N^2 \sin^2 \theta}, \quad (2.10)$$

indicating that the group velocity points in the direction of the characteristic paths. Using the dispersion relation (2.5), the expression (2.9) for Δ can also be rewritten as:

$$\Delta = (N^2 k_\rho k_\theta + \xi^2 k_r k_z)^2. \quad (2.11)$$

This expression implies that the group velocity (2.7) vanishes precisely when $\Delta = 0$, i.e., at turning points.

2.2. Local Frenet-Serret frame

Consider a characteristic path \mathcal{C} parametrized by an arclength $x_{\parallel} > 0$ that increases in the direction of wave propagation. At any point along the path, the position vector is given by

$$\mathbf{x}_0(x_{\parallel}) = r_0(x_{\parallel})\hat{\mathbf{e}}_r + z_0(x_{\parallel})\hat{\mathbf{e}}_z.$$

We define a local Frenet-Serret frame $(\hat{\mathbf{e}}_{\parallel}, \hat{\mathbf{e}}_{\perp})$ in the (r, z) plane as follows:

$$\frac{\partial \mathbf{x}_0}{\partial x_{\parallel}} = \hat{\mathbf{e}}_{\parallel}(x_{\parallel}) = r'_0(x_{\parallel})\hat{\mathbf{e}}_r + z'_0(x_{\parallel})\hat{\mathbf{e}}_z, \quad \hat{\mathbf{e}}_{\perp} = -z'_0(x_{\parallel})\hat{\mathbf{e}}_r + r'_0(x_{\parallel})\hat{\mathbf{e}}_z. \quad (2.12)$$

The vectors $\hat{\mathbf{e}}_{\parallel}$ and $\hat{\mathbf{e}}_{\perp}$ are orthonormal and satisfy the standard Frenet-Serret relations:

$$\frac{\partial \hat{\mathbf{e}}_{\parallel}}{\partial x_{\parallel}} = \kappa(x_{\parallel})\hat{\mathbf{e}}_{\perp}(x_{\parallel}), \quad \frac{\partial \hat{\mathbf{e}}_{\perp}}{\partial x_{\parallel}} = -\kappa(x_{\parallel})\hat{\mathbf{e}}_{\parallel}(x_{\parallel}), \quad (2.13)$$

where $\kappa(x_{\parallel})$ is the curvature of the characteristic path \mathcal{C} at the point $\mathbf{x}_0(x_{\parallel})$. It is given by

$$\kappa(x_{\parallel}) = z''_0(x_{\parallel})r'_0(x_{\parallel}) - r''_0(x_{\parallel})z'_0(x_{\parallel}). \quad (2.14)$$

The characteristic path $\mathbf{x}_0(x_{\parallel})$ satisfies the dispersion relation, which can be written as

$$\varpi^2 = \xi_0^2 r_0'^2 + N_0^2 \frac{(r_0 r'_0 + z_0 z'_0)^2}{\rho_0^2}, \quad (2.15)$$

where $\rho_0 = \sqrt{r_0^2 + z_0^2}$ is the local spherical radius, and $\xi_0 = \xi(r_0)$, $N_0 = N(\rho_0)$. The function $\Delta(x_{\parallel})$ can also be expressed along the characteristic path using equation (2.9) as:

$$\Delta(x_{\parallel}) = \varpi^2(N_0^2 + \xi_0^2 - \varpi^2) - N_0^2 \xi_0^2 z_0^2 / \rho_0^2. \quad (2.16)$$

Another useful expression for Δ , derived from the dispersion relation (2.15), is

$$\Delta(x_{\parallel}) = \frac{(N_0^2(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0) + \xi_0^2 r'_0 z'_0 \rho_0^2)^2}{\rho_0^4}. \quad (2.17)$$

This allows us to write

$$\epsilon_1 \sqrt{\Delta} = \frac{N_0^2(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0)}{\rho_0^2} + \xi_0^2 r'_0 z'_0 \quad (2.18)$$

where $\epsilon_1 = \text{sgn}[N_0^2(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0) + \xi_0^2 r'_0 z'_0 \rho_0^2]$. From this, we can derive the following additional expressions:

$$z'_0/r'_0 = \frac{N_0^2 r_0 z_0 / \rho_0^2 + \epsilon_1 \sqrt{\Delta}}{\varpi^2 - N_0^2 z_0^2 / \rho_0^2}, \quad (2.19a)$$

$$r'_0/z'_0 = \frac{N_0^2 r_0 z_0 / \rho_0^2 - \epsilon_1 \sqrt{\Delta}}{\varpi^2 - \xi_0^2 - N_0^2 r_0^2 / \rho_0^2}. \quad (2.19b)$$

The characteristic path \mathcal{C} may reach a turning point $\mathbf{x}_c = (r_c, z_c)$ at a specific value $x_{\parallel c}$ of the arclength parameter x_{\parallel} , where $\Delta = 0$. At this point, the characteristic path terminates and reflects, as illustrated in figure 1. It exhibits a generic cusp structure, which can be explicitly calculated under the assumption that the root of Δ is simple, that is,

$$\Delta(x_{\parallel c}) = \Delta_c = 0 \quad \text{and} \quad \Delta'(x_{\parallel c}) = \Delta'_c \neq 0.$$

Let us now investigate the form of the path in the local frame $(\hat{\mathbf{e}}_{\parallel c}, \hat{\mathbf{e}}_{\perp c})$ attached to the

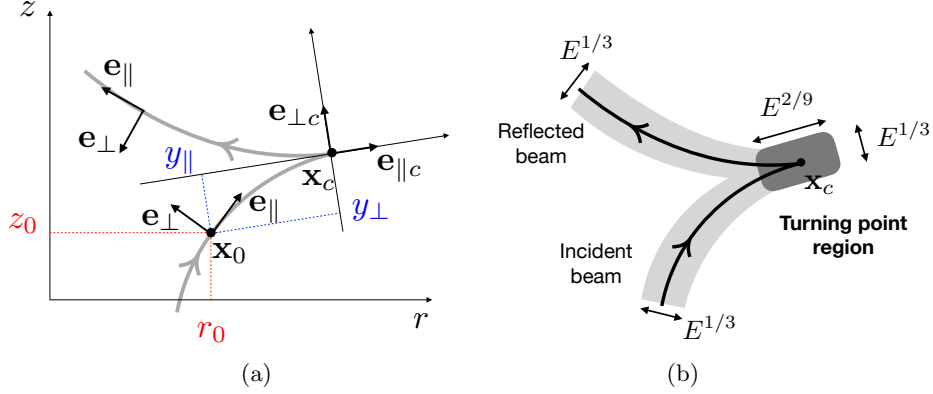


FIGURE 1. (a) Frames associated with the characteristic path close to a turning point \mathbf{x}_c . (b) Scaling of the turning point region for a viscous beam.

turning point \mathbf{x}_c (see figure 1(a)). If we express the path as $\mathbf{x}_0 = \mathbf{x}_c + y_{\parallel 0} \hat{\mathbf{e}}_{\parallel c} + y_{\perp 0} \hat{\mathbf{e}}_{\perp c}$, the coordinates $(y_{\parallel 0}, y_{\perp 0})$ satisfy, for x_\parallel close to $x_{\parallel c}$

$$y_{\parallel 0} \sim -|x_\parallel - x_{\parallel c}|, \quad y_{\perp 0} \sim \pm \frac{2}{3} \alpha_c |x_\parallel - x_{\parallel c}|^{3/2}, \quad (2.20)$$

which leads to the following relation between $y_{\perp 0}$ and $y_{\parallel 0}$:

$$y_{\perp 0} \sim \pm \frac{2}{3} \alpha_c (-y_{\parallel 0})^{3/2}. \quad (2.21)$$

Here, α_c is given by

$$\alpha_c = -\frac{\epsilon_1 z_c'^2 \sqrt{-\Delta_c'}}{\varpi^2 - \xi_c^2 - N_c^2 r_c^2 / \rho_c^2} = -\frac{\epsilon_1 r_c'^2 \sqrt{-\Delta_c'}}{\varpi^2 - N_c^2 z_c^2 / \rho_c^2} = -\frac{\epsilon_1 \sqrt{-\Delta_c'}}{2\varpi^2 - N_c^2 - \xi_c^2}, \quad (2.22)$$

where the subscript c denotes values evaluated at the turning point $x_{\parallel c}$. In equations (2.20b) and (2.21), the upper sign corresponds to the incident beam ($x_\parallel < x_{\parallel c}$) while the lower sign corresponds to the reflected beam ($x_\parallel > x_{\parallel c}$). If $N_c^2 r_c z_c \neq 0$, none of the denominators in (2.22) vanish, since

$$(\varpi^2 - \xi_c^2 - N_c^2 r_c^2 / \rho_c^2)(\varpi^2 - N_c^2 z_c^2 / \rho_c^2) = N_c^4 r_c^2 z_c^2 / \rho_c^4 > 0,$$

and

$$2\varpi^2 - \xi_c^2 - N_c^2 = (\varpi^2 - \xi_c^2 - N_c^2 r_c^2 / \rho_c^2) + (\varpi^2 - N_c^2 z_c^2 / \rho_c^2).$$

If $N_c^2 r_c z_c = 0$, then either $r_c' = 0$ and $\varpi^2 - \xi_c^2 - N_c^2 r_c^2 / \rho_c^2 = 0$, or $z_c' = 0$ and $\varpi^2 - N_c^2 z_c^2 / \rho_c^2 = 0$. In either case, the third expression of α_c remains valid.

It is important to note that the vectors $\hat{\mathbf{e}}_\perp$ and $\hat{\mathbf{e}}_\parallel$ associated with the reflected beam do not match $\hat{\mathbf{e}}_{\perp c}$ and $\hat{\mathbf{e}}_{\parallel c}$ as $x_\parallel \rightarrow x_{\parallel c}$. As a result, the functions r_0' and z_0' are not continuous across $x_{\parallel c}$. Throughout this analysis, all quantities evaluated at $x_{\parallel c}$ should be understood as taken in the limit $x_\parallel \rightarrow x_{\parallel c}^-$, i.e., for the incident beam.

Finally, it is interesting to note that the curvature κ also diverges at \mathbf{x}_c as

$$\kappa \sim -\frac{\alpha_c}{2\sqrt{|x_{\parallel c} - x_\parallel|}}. \quad (2.23)$$

2.3. Governing equations in the local frame of the characteristics

As we are interested in solutions localized around the characteristic path \mathcal{C} , it is useful to express the governing equations in the local coordinate system associated with this

path. We define the local variables $(x_{\parallel}, x_{\perp})$ of a point \mathbf{x} close to \mathcal{C} by writing:

$$\mathbf{x} = \mathbf{x}_0(x_{\parallel}) + x_{\perp} \hat{\mathbf{e}}_{\perp}, \quad \text{with} \quad \mathbf{x}_0(x_{\parallel}) = r_0(x_{\parallel}) \hat{\mathbf{e}}_r + z_0(x_{\parallel}) \hat{\mathbf{e}}_z, \quad (2.24)$$

where $\mathbf{x}_0(x_{\parallel})$ is the closest point to \mathbf{x} on \mathcal{C} . The differential vector increment can then be expressed as

$$\begin{aligned} d\mathbf{x} &= \frac{\partial \mathbf{x}_0}{\partial x_{\parallel}} dx_{\parallel} + \frac{\partial \mathbf{x}_0}{\partial \phi} d\phi + x_{\perp} \frac{\partial \hat{\mathbf{e}}_{\perp}}{\partial x_{\parallel}} dx_{\parallel} + \hat{\mathbf{e}}_{\perp} dx_{\perp} \\ &= (1 - \kappa x_{\perp}) dx_{\parallel} \hat{\mathbf{e}}_{\parallel} + dx_{\perp} \hat{\mathbf{e}}_{\perp} + r_0 d\phi \hat{\mathbf{e}}_{\phi}. \end{aligned} \quad (2.25)$$

which ensures that $(x_{\parallel}, x_{\perp}, \phi)$ forms an orthogonal curvilinear coordinate system with the metric components $(h_{\parallel}, h_{\perp}, h_{\phi}) = (1 - \kappa(x_{\parallel})x_{\perp}, 1, r_0(x_{\parallel}))$.

The governing equations (2.2) become, in this local coordinate system:

$$-i\varpi u_{\parallel} - 2\Omega(r)r'_0 u_{\phi} = -\frac{1}{h_{\parallel}} \frac{\partial p}{\partial x_{\parallel}} + b \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\parallel} + E(\nabla^2 \mathbf{u})_{\parallel}, \quad (2.26a)$$

$$-i\varpi u_{\perp} + 2\Omega(r)z'_0 u_{\phi} = -\frac{\partial p}{\partial x_{\perp}} + b \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\perp} + E(\nabla^2 \mathbf{u})_{\perp}, \quad (2.26b)$$

$$-i\varpi u_{\phi} + \omega(r)(r'_0 u_{\parallel} - z'_0 u_{\perp}) = E(\nabla^2 \mathbf{u})_{\phi}, \quad (2.26c)$$

$$\frac{\partial(r_0 u_{\parallel})}{\partial x_{\parallel}} + r_0 \frac{\partial(h_{\parallel} u_{\perp})}{\partial x_{\perp}} = 0, \quad (2.26d)$$

$$-i\varpi b + N^2(\rho)(u_{\parallel} \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\parallel} + u_{\perp} \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\perp}) = (E/Pr) \nabla^2 b, \quad (2.26e)$$

with the geometric relations:

$$\hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\parallel} = \frac{r_0 r'_0 + z_0 z'_0}{\rho}, \quad \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\perp} = \frac{z_0 r'_0 - r_0 z'_0 + x_{\perp}}{\rho}, \quad (2.27)$$

and the coordinate transformations:

$$r = r_0 - z'_0 x_{\perp}, \quad z = z_0 + r'_0 x_{\perp}, \quad \rho = \sqrt{r^2 + z^2}. \quad (2.28)$$

3. Viscous solutions localized around a characteristic path

In this section, we develop an approximation for a viscous/diffusive solution that is localized on the characteristic path \mathcal{C} . Our goal is to extend the solutions derived by Moore & Saffman (1969) and Thomas & Stevenson (1972), originally obtained for purely rotating or purely stratified fluid, to the more general case of a non-uniformly rotating and stratified fluid.

Guided by their approach, we introduce a stretched transverse coordinate:

$$\bar{x}_{\perp} = \frac{x_{\perp}}{E^{1/3}}, \quad (3.1)$$

and make the following ansatz:

$$u_{\parallel} = u_{\parallel}^{(0)}(x_{\parallel}, \bar{x}_{\perp}) + \dots, \quad (3.2a)$$

$$u_{\perp} = E^{1/3} u_{\perp}^{(1)}(x_{\parallel}, \bar{x}_{\perp}) + \dots, \quad (3.2b)$$

$$u_{\phi} = u_{\phi}^{(0)}(x_{\parallel}, \bar{x}_{\perp}) + \dots, \quad (3.2c)$$

$$b = b^{(0)}(x_{\parallel}, \bar{x}_{\perp}) + \dots, \quad (3.2d)$$

$$p = E^{1/3} p^{(1)}(x_{\parallel}, \bar{x}_{\perp}) + \dots \quad (3.2e)$$

This ansatz assumes that the solution is mainly oriented along \mathbf{e}_\parallel (in the (x,z) plane) and depends on a single fast variable \bar{x}_\perp , corresponding to a beam width $E^{1/3}$ smaller than the background variation scale.

From equations (2.26c,e), the leading-order relations between $u_\parallel^{(0)}$, $u_\phi^{(0)}$ and $b^{(0)}$ are:

$$u_\phi^{(0)} = -\frac{i\omega_0 r'_0}{\varpi} u_\parallel^{(0)}, \quad (3.3a)$$

$$b^{(0)} = -\frac{iN_0^2}{\varpi} \frac{r_0 r'_0 + z_0 z'_0}{\rho_0} u_\parallel^{(0)}, \quad (3.3b)$$

with $\rho_0 = \sqrt{r_0^2 + z_0^2}$, where, we recall, $N_0 = N(\rho_0)$ and $\omega_0 = \omega(r_0)$. From the leading order balance of equation (2.26b), we obtain:

$$\frac{\partial p^{(1)}}{\partial \bar{x}_\perp} = -2\Omega_0 z'_0 u_\phi^{(0)} - \frac{r_0 z'_0 - z_0 r'_0}{\rho_0} b^{(0)}.$$

Substituting expressions from (3.3a,b) yields

$$\frac{\partial p^{(1)}}{\partial \bar{x}_\perp} = \frac{i}{\varpi} \left(\xi_0^2 r'_0 z'_0 + N_0^2 \frac{(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0)}{\rho_0^2} \right) u_\parallel^{(0)}. \quad (3.4)$$

Now consider the operation $i\varpi(2.26a) - 2\Omega r'_0(2.26c) - \hat{\mathbf{e}}_\rho \cdot \hat{\mathbf{e}}_\parallel(2.26e)$, which gives:

$$\begin{aligned} & \left(\varpi^2 - \xi^2 r_0'^2 - N^2 \frac{(r_0 r'_0 + z_0 z'_0)^2}{\rho^2} \right) (u_\parallel^{(0)} + E^{1/3} u_\parallel^{(1)}) (1 - \kappa_0 \bar{x}_\perp E^{1/3}) \\ &= -E^{1/3} \left(\xi_0^2 r'_0 z'_0 + N_0^2 \frac{(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0)}{\rho_0^2} \right) u_\perp^{(1)} - iE^{1/3} \varpi \frac{\partial p^{(1)}}{\partial x_\parallel} \\ &+ E^{1/3} \left(i\varpi \frac{\partial^2 u_\parallel^{(0)}}{\partial \bar{x}_\perp^2} - 2\Omega_0 r'_0 \frac{\partial^2 u_\phi^{(0)}}{\partial \bar{x}_\perp^2} - \frac{1}{Pr} \frac{(r_0 r'_0 + z_0 z'_0)}{\rho_0} \frac{\partial^2 b^{(0)}}{\partial \bar{x}_\perp^2} \right) + O(E^{2/3}). \end{aligned} \quad (3.5)$$

Due to the dispersion relation (2.15), the left-hand side reduces to

$$E^{1/3} [\partial_r(\xi^2)_0 r_0'^2 z'_0 + \partial_\rho(N^2/\rho^2)_0 (r_0 r'_0 + z_0 z'_0)^2 (r_0 z'_0 - z_0 r'_0)] \bar{x}_\perp u_\parallel^{(0)}.$$

Taking the derivative with respect to \bar{x}_\perp and substituting $\partial_{\bar{x}_\perp} p^{(1)}$ from (3.4), $u_\phi^{(0)}$ and $b^{(0)}$ from (3.3a,b), and using the expression for $\partial_{\bar{x}_\perp} u_\perp^{(1)}$ from equation (2.26d):

$$\frac{\partial u_\perp^{(1)}}{\partial \bar{x}_\perp} = -\frac{1}{r_0} \frac{\partial(r_0 u_\parallel^{(0)})}{\partial x_\parallel}, \quad (3.6)$$

we finally obtain a single equation for $u_\parallel^{(0)}$:

$$\begin{aligned} & \left(\xi_0^2 r'_0 z'_0 + N_0^2 \frac{(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0)}{\rho_0^2} \right) \frac{1}{r_0} \frac{\partial(r_0 u_\parallel^{(0)})}{\partial x_\parallel} = \\ & -\frac{\partial}{\partial x_\parallel} \left[\left(\xi_0^2 r'_0 z'_0 + N_0^2 \frac{(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0)}{\rho_0^2} \right) u_\parallel^{(0)} \right] \\ & -\frac{i}{\varpi} \left(2\xi_0^2 r_0'^2 + \left(1 + \frac{1}{Pr} \right) N_0^2 \frac{(r_0 r'_0 + z_0 z'_0)^2}{\rho_0^2} \right) \frac{\partial^3 u_\parallel^{(0)}}{\partial \bar{x}_\perp^3} \\ & + [\partial_r(\xi^2)_0 r_0'^2 z'_0 + \partial_\rho(N^2/\rho^2)_0 (r_0 r'_0 + z_0 z'_0)^2 (r_0 z'_0 - z_0 r'_0)] \frac{\partial(\bar{x}_\perp u_\parallel^{(0)})}{\partial \bar{x}_\perp}. \end{aligned} \quad (3.7)$$

If we now introduce the new function \tilde{u}_\parallel and the new variables \tilde{x}_\parallel and \tilde{x}_\perp defined by

$$u_\parallel^{(0)}(\bar{x}_\perp, x_\parallel) = \frac{F(x_\parallel)}{\sqrt{r_0|K(x_\parallel)|}} \tilde{u}_\parallel(\tilde{x}_\perp, \tilde{x}_\parallel), \quad (3.8a)$$

$$\tilde{x}_\parallel = \int_{x_\parallel^{(0)}}^{x_\parallel} \frac{DF^3}{2K} dx_\parallel + \tilde{x}_\parallel^{(0)}, \quad (3.8b)$$

$$\tilde{x}_\perp = F(x_\parallel) \bar{x}_\perp, \quad (3.8c)$$

with

$$K(x_\parallel) = \xi_0^2 r'_0 z'_0 + N_0^2 \frac{(r_0 r'_0 + z_0 z'_0)(r_0 z'_0 - z_0 r'_0)}{\rho_0^2}, \quad (3.9a)$$

$$H(x_\parallel) = \partial_r(\xi^2)_0 r'_0 z'_0 + \partial_\rho(N^2/\rho^2)_0 (r_0 r'_0 + z_0 z'_0)^2 (r_0 z'_0 - z_0 r'_0), \quad (3.9b)$$

$$D(x_\parallel) = \frac{2\xi_0^2 r'^2_0 \rho_0^2 + (1 + Pr^{-1})N_0^2 (r_0 r'_0 + z_0 z'_0)^2}{\varpi \rho_0^2}, \quad (3.9c)$$

$$F(x_\parallel) = \exp\left(\int_{x_\parallel^{(0)}}^{x_\parallel} \frac{H}{2K} dx_\parallel\right), \quad (3.9d)$$

then equation (3.7) becomes the parameter-free equation

$$\frac{\partial \tilde{u}_\parallel}{\partial \tilde{x}_\parallel} = -i \frac{\partial^3 \tilde{u}_\parallel}{\partial \tilde{x}_\perp^3}. \quad (3.10)$$

In equations (3.8b) and (3.9d), the parameter $x_\parallel^{(0)} > 0$ corresponds to the arclength at which we start considering the solution, and $\tilde{x}_\parallel^{(0)}$ is an arbitrary constant. The functions K , H and D can also be expressed in terms of the angles $\theta = \text{atan}(z_0/r_0)$ and $\phi = \text{atan}(z'_0/r'_0)$ as

$$K = \xi_0^2 \cos \phi \sin \phi + N_0^2 \cos(\phi - \theta) \sin(\phi - \theta) \quad (3.11a)$$

$$H = \partial_r(\xi^2)_0 \cos^2 \phi \sin \phi + \rho_0^2 \partial_\rho(N^2/\rho^2)_0 \cos^2(\phi - \theta) \sin(\phi - \theta) \quad (3.11b)$$

$$D = \frac{2\xi_0^2 \cos^2 \phi + (1 + Pr^{-1})N_0^2 \cos^2(\phi - \theta)}{\varpi}, \quad (3.11c)$$

The function H contains the terms associated with the spatial variations of the background rotation and stratification. It can also be written as

$$H = - \left. \frac{\partial \varpi_{nv}^2}{\partial x_\perp} \right|_0, \quad (3.12)$$

where

$$\varpi_{nv}^2(r, z, \phi) = \xi^2(r) \cos^2 \phi + N^2(\rho)(r \cos \phi + z \sin \phi)^2 / \rho^2$$

is the local inviscid dispersion relation, and r and z depend on x_\perp according to (2.28).

Equation (3.10) is the same as the one obtained by Moore & Saffman (1969) and Thomas & Stevenson (1972). It can be easily solved using a Fourier transform in \tilde{x}_\perp , yielding a general solution:

$$\tilde{u}_\parallel(\tilde{x}_\perp, \tilde{x}_\parallel) = \int_{-\infty}^{\infty} a(k) e^{-k^3 \tilde{x}_\parallel} e^{ik \tilde{x}_\perp} dk. \quad (3.13)$$

A localized solution was also obtained by Kistovich & Chashechkin (1998) for a 2D vertically stratified fluid. They used a global WKB ansatz, taking advantage of the separability of the problem in that case. If we apply our analysis to this configuration for which $N = N(z)$ and $\xi = 0$, we obtain

$$\varpi^2 = N_0^2 z_0'^2, \quad K = N_0^2 z_0' r_0' = \varpi^2 r_0' / z_0', \quad H = \partial_z (N^2)_0 r_0' z_0'^2 \quad (3.14a)$$

$$D = (1 + Pr^{-1})\varpi, \quad F = N_0 = \frac{\varpi}{|z_0'|}, \quad (3.14b)$$

which gives

$$u_{\parallel}^{(0)} = |z_0' r_0'|^{-1/2} \tilde{u}_{\parallel}(\tilde{x}_{\perp}, \tilde{x}_{\parallel}), \quad (3.15a)$$

$$\tilde{x}_{\perp} = \frac{\varpi}{|z_0'|} \bar{x}_{\perp}, \quad \tilde{x}_{\parallel} = \frac{(1 + Pr^{-1})\varpi^2}{2} \int_{x_{\parallel}^{(0)}}^{x_{\parallel}} \frac{dx_{\parallel}}{r_0' z_0'^2} + \tilde{x}_{\parallel}^{(0)}. \quad (3.15b)$$

These expressions are identical to Eqs (2.5) and (2.6) of Kistovich & Chashechkin (1998), once the solution is expressed in terms of \bar{x}_{\perp} .

In the denominator of equation (3.8b), we recognize the expression (2.18) for $\epsilon_1 \sqrt{\Delta}$. For $x_{\parallel} > x_{\parallel}^{(0)}$, the sign of \tilde{x}_{\parallel} depends on the value of ϵ_1 . The solutions propagating along \mathcal{C} in the direction of increasing x_{\parallel} consist of positive wavenumbers ($a(k < 0) = 0$) if $\epsilon_1 = 1$, and negative wavenumbers ($a(k > 0) = 0$) if $\epsilon_1 = -1$. Hence, the solutions propagating along \mathcal{C} in the direction of increasing x_{\parallel} can be written as

$$\tilde{u}_{\parallel}(\tilde{x}_{\perp}, \tilde{x}_{\parallel}) = \int_0^{\infty} b(k) e^{-k^3 \epsilon_1 \tilde{x}_{\parallel}} e^{ik \epsilon_1 \tilde{x}_{\perp}} dk. \quad (3.16)$$

When the incident beam reaches the turning point $x_{\parallel c}$, the viscous solution given by (3.8a-c) and (3.9a-d) breaks down, as the amplitude prefactor in the expression (3.8a) for $u_{\parallel}^{(0)}$ diverges (this term is proportional to $\Delta^{-1/4}$, see expression (2.18)). While the denominators in \tilde{x}_{\parallel} and F in (3.8b) and (3.9d) vanish at this point, the integrals remain convergent. The behavior near the turning point can be obtained by taking $x_{\parallel} \rightarrow x_{\parallel c}$ in (3.8a-c). We obtain:

$$u_{\parallel}^{(0)} \sim \frac{F_c}{\sqrt{r_c} |-\Delta'_c(x_{\parallel c} - x_{\parallel})|^{1/4}} \tilde{u}_{\parallel}(F_c \bar{x}_{\perp}, \tilde{x}_{\parallel c}). \quad (3.17)$$

This expression can be written in terms of the local variable $(y_{\parallel}, y_{\perp})$ when $x_{\parallel} \rightarrow x_{\parallel c}$ using the approximations

$$x_{\parallel c} - x_{\parallel} \sim -y_{\parallel 0} = -y_{\parallel}, \quad x_{\perp} \sim y_{\perp} - y_{\perp 0} \sim y_{\perp} - \frac{2}{3} \alpha_c (-y_{\parallel})^{3/2}. \quad (3.18)$$

Since $x_{\perp} = O(E^{1/3})$, the second relation implies that $y_{\perp} = O(E^{1/3})$ and $y_{\parallel} = O(E^{2/9})$ in the vicinity of the turning point. We will use this scaling to analyse the behavior of the solution near the turning point region in the next section.

Note that, in expression (3.16), if we choose

$$b(k) = b^S(k) \equiv k^{m-1} \frac{e^{-im\pi/2}}{(m-1)!}, \quad \text{with } m > 0, \quad (3.19)$$

we recover the similarity solution derived by Moore & Saffman (1969) and Thomas &

Stevenson (1972):

$$\tilde{u}_{\parallel} = \tilde{u}_{\parallel}^S \equiv |\tilde{x}_{\parallel}|^{-m/3} h_m(\eta) \quad , \quad \eta = \epsilon_1 \frac{\tilde{x}_{\perp}}{|\tilde{x}_{\parallel}|^{1/3}} = \epsilon_1 \frac{\bar{x}_{\perp}}{|\tilde{x}_{\parallel}/F^3|^{1/3}}, \quad (3.20)$$

where the function $h_m(\eta)$ is defined as

$$h_m(\eta) = \frac{e^{-im\pi/2}}{(m-1)!} \int_0^{\infty} e^{-p^3} e^{ip\eta} p^{m-1} dp. \quad (3.21)$$

The normalization of the function h_m ensures the following asymptotic behavior:

$$h_m(\eta) \underset{\eta \rightarrow +\infty}{\sim} |\eta|^{-m}, \quad (3.22a)$$

$$h_m(\eta) \underset{\eta \rightarrow -\infty}{\sim} e^{-im\pi} |\eta|^{-m}. \quad (3.22b)$$

This implies that the similarity solution \tilde{u}_{\parallel}^S behaves as

$$\tilde{u}_{\parallel}^S \underset{\epsilon_1 \tilde{x}_{\perp} \rightarrow +\infty}{\sim} |\tilde{x}_{\perp}|^{-m}, \quad (3.23a)$$

$$\tilde{u}_{\parallel}^S \underset{\epsilon_1 \tilde{x}_{\perp} \rightarrow -\infty}{\sim} e^{-im\pi} |\tilde{x}_{\perp}|^{-m}. \quad (3.23b)$$

These behaviours demonstrate that expression (3.20) defines a viscous solution associated with an inviscid singularity of the form $|x_{\perp}|^{-m}$ along the characteristic path \mathcal{C} . The definition (3.20) of the similarity variable η shows that this singularity originates at $\tilde{x}_{\parallel} = 0$. The width of the wave beam is given by $|\tilde{x}_{\parallel}|^{1/3}/F$, where \tilde{x}_{\parallel} and F evolve according to (3.8b) and (3.9d), respectively.

4. Solution close to the turning point and reflected beam

We have seen in the previous section that the solution described by (3.8a,b) and (3.16) breaks down upon reaching a turning point. In this section, our objective is to derive a new approximation that remains valid in the vicinity of a turning point. To this end, we adopt the local frame $(\hat{\mathbf{e}}_{\parallel c}, \hat{\mathbf{e}}_{\perp c})$ and the local coordinates $(y_{\parallel}, y_{\perp})$.

In this frame, if we denote the velocity components along $\hat{\mathbf{e}}_{\parallel c}$ and $\hat{\mathbf{e}}_{\perp c}$ by v_{\parallel} and v_{\perp} , respectively, the governing equations become:

$$-i\varpi v_{\parallel} - 2\Omega r'_c u_{\phi} = -\frac{\partial p}{\partial y_{\parallel}} + b \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\parallel c} + E \nabla^2 v_{\parallel}, \quad (4.1a)$$

$$-i\varpi v_{\perp} + 2\Omega z'_c u_{\phi} = -\frac{\partial p}{\partial y_{\perp}} + b \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\perp c} + E \nabla^2 v_{\perp}, \quad (4.1b)$$

$$-i\varpi u_{\phi} + \omega(r'_c v_{\parallel} - z'_c v_{\perp}) = E \nabla^2 u_{\phi}, \quad (4.1c)$$

$$\frac{\partial r v_{\parallel}}{\partial y_{\parallel}} + r \frac{\partial v_{\perp}}{\partial y_{\perp}} = 0, \quad (4.1d)$$

$$-i\varpi b + N^2(v_{\parallel} \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\parallel c} + v_{\perp} \hat{\mathbf{e}}_{\rho} \cdot \hat{\mathbf{e}}_{\perp c}) = (E/Pr) \nabla^2 b. \quad (4.1e)$$

We now introduce the following ansatz:

$$v_{\parallel} = v_{\parallel}^{(0)}, \quad v_{\perp} = E^{1/9} v_{\perp}^{(1)}, \quad u_{\phi} = u_{\phi}^{(0)}, \quad b = b^{(0)}, \quad p = E^{4/9} p^{(4)}, \quad (4.2)$$

together with the rescaled local variables:

$$\bar{y}_{\parallel} = E^{-2/9} y_{\parallel}, \quad \bar{y}_{\perp} = E^{-1/3} y_{\perp}. \quad (4.3)$$

Under this scaling, the governing equations reduce to:

$$-i\varpi v_{\parallel}^{(0)} - 2\Omega r'_c u_{\phi}^{(0)} = -E^{2/9} \frac{\partial p^{(4)}}{\partial \bar{y}_{\parallel}} + b^{(0)}(rr'_c + zz'_c)/\rho, \quad (4.4a)$$

$$-i\varpi E^{1/9} v_{\perp}^{(1)} + 2\Omega z'_c u_{\phi}^{(0)} = -E^{1/9} \frac{\partial p^{(4)}}{\partial \bar{y}_{\perp}} + b^{(0)}(zr'_c - rz'_c)/\rho, \quad (4.4b)$$

$$-i\varpi u_{\phi}^{(0)} + \omega(r'_c v_{\parallel}^{(0)} - z'_c v_{\perp}^{(1)} E^{1/9}) = 0, \quad (4.4c)$$

$$\frac{\partial v_{\parallel}^{(0)}}{\partial \bar{y}_{\parallel}} + \frac{\partial v_{\perp}^{(1)}}{\partial \bar{y}_{\perp}} = 0, \quad (4.4d)$$

$$-i\varpi b^{(0)} + (N^2/\rho)(v_{\parallel}^{(0)}(rr'_c + zz'_c) + E^{1/9} v_{\perp}^{(1)}(zr'_c - rz'_c)) = 0. \quad (4.4e)$$

Note that viscous terms do not appear in these equations.

From equations (4.4c,e), we express $u_{\phi}^{(0)}$ and $b^{(0)}$ in terms of $v_{\parallel}^{(0)}$ and $v_{\perp}^{(1)}$:

$$u_{\phi}^{(0)} = \frac{\omega}{i\varpi}(r'_c v_{\parallel}^{(0)} - z'_c E^{1/9} v_{\perp}^{(1)}), \quad (4.5a)$$

$$b^{(0)} = \frac{N^2}{i\varpi\rho}(v_{\parallel}^{(0)}(rr'_c + zz'_c) - E^{1/9} v_{\perp}^{(1)}(rz'_c - zr'_c)). \quad (4.5b)$$

Substituting these into equations (4.4a,b) yields:

$$-\frac{\Delta'_c}{i\varpi(2\varpi^2 - \xi_c^2 - N_c^2)} \bar{y}_{\parallel} v_{\parallel}^{(0)} = -\frac{\partial p^{(4)}}{\partial \bar{y}_{\parallel}}, \quad (4.6a)$$

$$\frac{2\varpi^2 - \xi_c^2 - N_c^2}{i\varpi} v_{\perp}^{(1)} = -\frac{\partial p^{(4)}}{\partial \bar{y}_{\perp}}, \quad (4.6b)$$

where we have used the following estimates, deduced from equations (2.15), (2.16) and (2.17) near the turning point r_c :

$$2\Omega\omega r'_c z'_c + N^2(rr'_c + zz'_c)(rz'_c - zr'_c)/\rho^2 = O(E^{2/9}),$$

$$-\varpi^2 + 2\Omega\omega z_c'^2 + N^2(rz'_c - zr'_c)^2/\rho^2 \sim -2\varpi^2 + \xi_c^2 + N_c^2,$$

$$-\varpi^2 + 2\Omega\omega r_c'^2 + N^2(rr'_c + zz'_c)^2/\rho^2 \sim E^{2/9} \frac{\Delta'_c}{2\varpi^2 - \xi_c^2 - N_c^2} \bar{y}_{\parallel}.$$

Eliminating $p^{(4)}$ and $v_{\perp}^{(1)}$ using (4.4d) finally gives a single equation for $v_{\parallel}^{(0)}$

$$\frac{\partial^2 v_{\parallel}^{(0)}}{\partial \bar{y}_{\parallel}^2} - \frac{\Delta'_c \bar{y}_{\parallel}}{(2\varpi^2 - \xi_c^2 - N_c^2)^2} \frac{\partial^2 v_{\parallel}^{(0)}}{\partial \bar{y}_{\perp}^2} = 0. \quad (4.7)$$

This equation can be solved using a Fourier transform in the \bar{y}_{\perp} direction:

$$v_{\parallel}^{(0)} = \int_{-\infty}^{+\infty} \tilde{v}_{\parallel} e^{ik\bar{y}_{\perp}} dk \quad (4.8)$$

such that \tilde{v}_{\parallel} satisfies the Airy equation

$$\frac{\partial^2 \tilde{v}_{\parallel}}{\partial \bar{y}_{\parallel}^2} - \tilde{y}_{\parallel} \tilde{v}_{\parallel} = 0, \quad (4.9)$$

with

$$\tilde{y}_{\parallel} = \gamma|k|^{2/3}\bar{y}_{\parallel}, \quad (4.10)$$

and

$$\gamma = \left(\frac{-\Delta'_c}{(2\varpi^2 - \xi_c^2 - N_c^2)^2} \right)^{1/3}. \quad (4.11)$$

Finding an Airy equation near a turning point is not a surprise (Wasow, 1985). Such an equation was derived in the context of non-rotating fluids by Sutherland (2010) for plane waves and by Kistovich & Chashechkin (1998) for concentrated beams.

The solution to the Airy equation (4.9) that remains bounded for large $|\tilde{y}_{\parallel}|$ is

$$\tilde{v}_{\parallel} = c(k) \text{Ai}(\tilde{y}_{\parallel}), \quad (4.12)$$

where Ai is an Airy function (Abramowitz & Stegun, 1965, p. 446), and $c(k)$ is a function to be determined by matching.

Using the asymptotic expansion of the Airy function as $\tilde{y}_{\parallel} \rightarrow -\infty$ (Abramowitz & Stegun, 1965, p. 448), we obtain:

$$\tilde{v}_{\parallel} \sim \frac{c(k)}{\sqrt{\pi}(-\tilde{y}_{\parallel})^{1/4}} \sin\left(\frac{2}{3}(-\tilde{y}_{\parallel})^{3/2} + \frac{\pi}{4}\right). \quad (4.13)$$

This leads to the following asymptotic form for $v_{\parallel}^{(0)}$:

$$\begin{aligned} v_{\parallel}^{(0)} \sim \int_{-\infty}^{+\infty} \frac{C(k)}{(-\bar{y}_{\parallel})^{1/4}} \left\{ \exp\left[ik\left(\bar{y}_{\perp} + \frac{2|k|}{3k}\gamma^{3/2}(-\bar{y}_{\parallel})^{3/2}\right) - i\pi/4\right] \right. \\ \left. + \exp\left[ik\left(\bar{y}_{\perp} - \frac{2|k|}{3k}\gamma^{3/2}(-\bar{y}_{\parallel})^{3/2}\right) + i\pi/4\right] \right\} dk, \end{aligned} \quad (4.14)$$

with

$$C(k) = \frac{c(k)}{2\sqrt{\pi}\gamma^{1/4}|k|^{1/6}}. \quad (4.15)$$

Each wave beam corresponds to a prescribed sign of the axial wavenumber k . Expression (4.14) is therefore a sum of four wave beams, corresponding to positive and negative wavenumbers propagating along two distinct paths: $\bar{y}_{\perp} = \frac{2}{3}\gamma^{3/2}(-\bar{y}_{\parallel})^{3/2}$ and $\bar{y}_{\perp} = -\frac{2}{3}\gamma^{3/2}(-\bar{y}_{\parallel})^{3/2}$. Only one of these corresponds to the incident beam. Using (3.17) and (3.18), the expression for the incident beam in terms of the local variable is

$$u_{\parallel}^{(0)} \sim \frac{\int_0^{+\infty} b(k/F_c) e^{-k^3 \epsilon_1 \tilde{x}_{\parallel c}/F_c^3} e^{ik\epsilon_1(\bar{y}_{\perp} - \frac{2}{3}\alpha_c(-\bar{y}_{\parallel})^{3/2})} dk}{r_c^{1/2}(-\Delta'_c)^{1/4}(-\bar{y}_{\parallel})^{1/4}E^{1/18}}. \quad (4.16)$$

From (2.22), we can write

$$\alpha_c = -\epsilon_1 \epsilon_2 \gamma^{3/2}, \quad (4.17)$$

with $\epsilon_2 = \text{sgn}(2\varpi^2 - \xi_c^2 - N_c^2)$. We then immediately see that the incident beam corresponds to the second term in (4.14) if $\epsilon_2 > 0$, but to the first term if $\epsilon_2 < 0$. The condition of matching then imposes the following relation between $C(k)$ in (4.14) and $b(k)$ in (4.16):

$$C(k) = \frac{H(\epsilon_1 k) b(\epsilon_1 k/F_c)}{r_c^{1/2}(-\Delta'_c)^{1/4}E^{1/18}} e^{-k^3 \tilde{x}_{\parallel c}/F_c^3} e^{i\epsilon_2 \pi/4}, \quad (4.18)$$

where $H(z)$ is the Heaviside function.

Expression (4.18) for $C(k)$ implies the following expression for $c(k)$ appearing in (4.12):

$$c(k) = \frac{H(\epsilon_1 k) b(\epsilon_1 k / F_c) 2\sqrt{\pi} \gamma^{1/4} |k|^{1/6}}{r_c^{1/2} (-\Delta'_c)^{1/4} E^{1/18}} e^{-k^3 \tilde{x}_{\parallel c} / F_c^3} e^{i\epsilon_2 \pi / 4}. \quad (4.19)$$

For the similarity solution obtained with $b(k)$ given by (3.19), we obtain the following expression for the solution in the turning point region:

$$v_{\parallel} = C_t V_m^S(Y_{\parallel}, Y_{\perp}), \quad (4.20)$$

where

$$V_m^S(Y_{\parallel}, Y_{\perp}) \equiv \int_0^{\infty} k^{m-1+1/6} \text{Ai}(k^{2/3} Y_{\parallel}) e^{ik Y_{\perp}} e^{-k^3} dk, \quad (4.21)$$

and

$$C_t = \frac{2\sqrt{\pi} \gamma^{1/4} F_c^{7/6}}{\tilde{x}_{\parallel c}^{(m+1/6)/3} r_c^{1/2} (-\Delta'_c)^{1/4} E^{1/18}} \frac{e^{-im\pi/2}}{(m-1)!} e^{i\epsilon_2 \pi / 4}, \quad (4.22a)$$

$$Y_{\parallel} = \frac{\gamma F_c^{2/3} y_{\parallel}}{|\tilde{x}_{\parallel c}|^{2/9} E^{2/9}}, \quad (4.22b)$$

$$Y_{\perp} = \frac{\epsilon_1 F_c y_{\perp}}{|\tilde{x}_{\parallel c}|^{1/3} E^{1/3}}. \quad (4.22c)$$

We recall that γ is defined in (4.11), Δ in (2.9), \tilde{x}_{\parallel} in (3.8b) and F in (3.9d).

Contour plots of the real part, imaginary part, norm and phase of the function V_1^S in the $(Y_{\parallel}, Y_{\perp})$ plane are shown in figure 2. The real part $\Re(V_m^S)$ is even with respect to the variable Y_{\perp} while the imaginary part $\Im(V_m^S)$ is odd in Y_{\perp} . As time evolves, the velocity field is expected to oscillate between these two components. As seen in figure 2(c), $|V_m^S|$ is localized around the ray trajectory defined by $Y_{\perp} = \pm(-Y_{\parallel})^{3/2}$ for $Y_{\parallel} \leq 0$. For positive Y_{\parallel} , $|V_m^S|$ becomes evanescent, i.e., it decays exponentially as Y_{\parallel} increases, consistent with the known behavior of the Airy function Ai for positive arguments. This agrees with the physical expectation that no waves propagate beyond the turning point located at the origin. In figure 2(d), we can observe how the phase of the beam changes as it passes through the turning point.

The other term in (4.14) corresponds to the reflected beam. It has the same form as the incident beam expression (4.16), but it is now localized along the path $\bar{y} = -(2/3)\alpha_c(-\bar{y}_{\parallel})^{3/2}$. If we express this term in the coordinates associated with the reflected beam, which is such that $\hat{\mathbf{e}}_{\parallel}$ and $\hat{\mathbf{e}}_{\perp}$ are reversed compared to those of the incident beam (see figure 1), we obtain

$$u_{\parallel R}^{(0)} \sim - \frac{e^{i\epsilon_2 \pi / 2} \int_0^{+\infty} b(k/F_c) e^{-k^3 \epsilon_1 \tilde{x}_{\parallel c} / F_c^3} e^{ik \epsilon_1 (\bar{y}_{\perp} + \frac{2}{3} \alpha_c (-\bar{y}_{\parallel})^{3/2})} dk}{r_c^{1/2} (-\Delta'_c)^{1/4} (-\bar{y}_{\parallel})^{1/4} E^{1/18}}. \quad (4.23)$$

This yields an expression for the reflected beam of the same form as (3.8) as we move

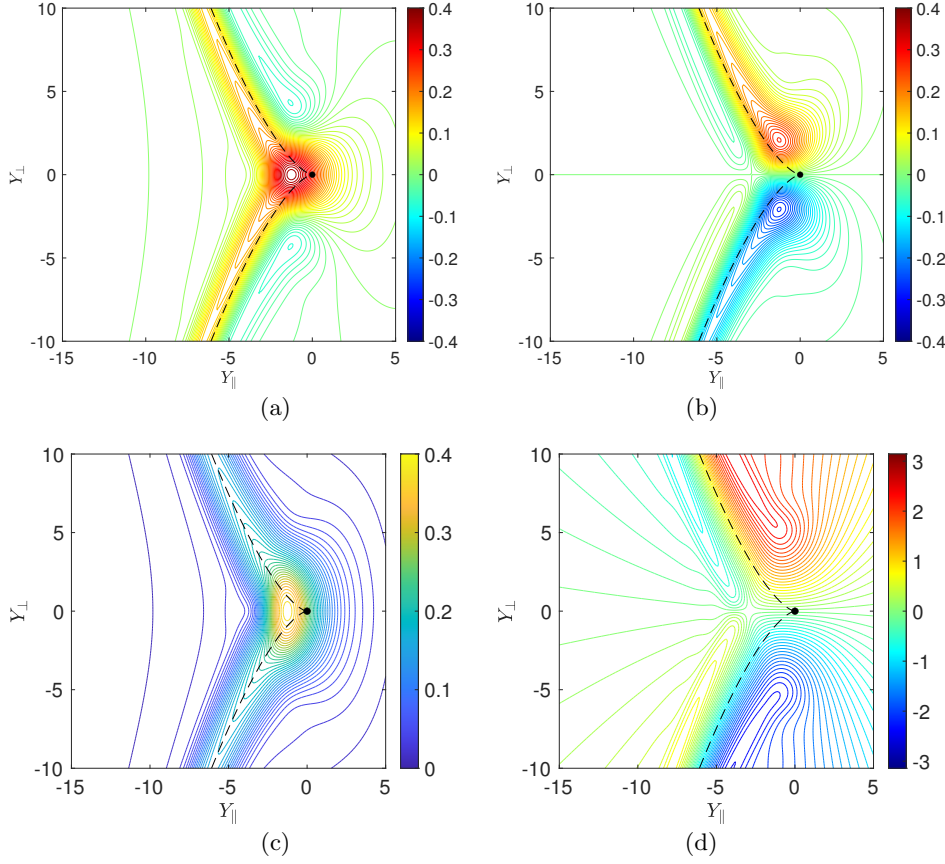


FIGURE 2. Contour plot of the function V_m^S in the $(Y_{\parallel}, Y_{\perp})$ plane for $m = 1$. Dashed black lines indicate the ray trajectory ($Y_{\perp} = \pm(-Y_{\parallel})^{3/2}$) as it reflects at the turning point (black circle at the origin). (a) Real part of V_m^S . (b) Imaginary part of V_m^S . (c) Absolute value of V_m^S . (d) Phase of V_m^S .

away from the turning point:

$$u_{\parallel R}^{(0)}(\tilde{x}_{\perp}, x_{\parallel}) = \frac{F(x_{\parallel})}{\sqrt{r_0|K(x_{\parallel})|}} \tilde{u}_{\parallel R}(\tilde{x}_{\perp}, \tilde{x}_{\parallel}), \quad (4.24a)$$

$$\tilde{x}_{\parallel} = \int_{x_{\parallel c}}^{x_{\parallel}} \frac{DF^3}{2K} dx_{\parallel} + \tilde{x}_{\parallel c}, \quad (4.24b)$$

$$\tilde{x}_{\perp} = F(x_{\parallel}) \bar{x}_{\perp}, \quad (4.24c)$$

$$F(x_{\parallel}) = \exp \left(\int_{x_{\parallel c}}^{x_{\parallel}} \frac{H}{2K} dx_{\parallel} \right) \quad (4.24d)$$

where K , H and D are defined in (3.9a-c) and $\tilde{u}_{\parallel R}(\tilde{x}_{\perp}, \tilde{x}_{\parallel})$ is given by

$$\tilde{u}_{\parallel R} = e^{-i\epsilon_2\pi/2} \int_0^{\infty} b(k) e^{-k^3\epsilon_1\tilde{x}_{\parallel}} e^{-ik\epsilon_1\tilde{x}_{\perp}} dk. \quad (4.25)$$

This matches the form of the incident beam expression in (3.16), if we replace \tilde{x}_{\perp} by

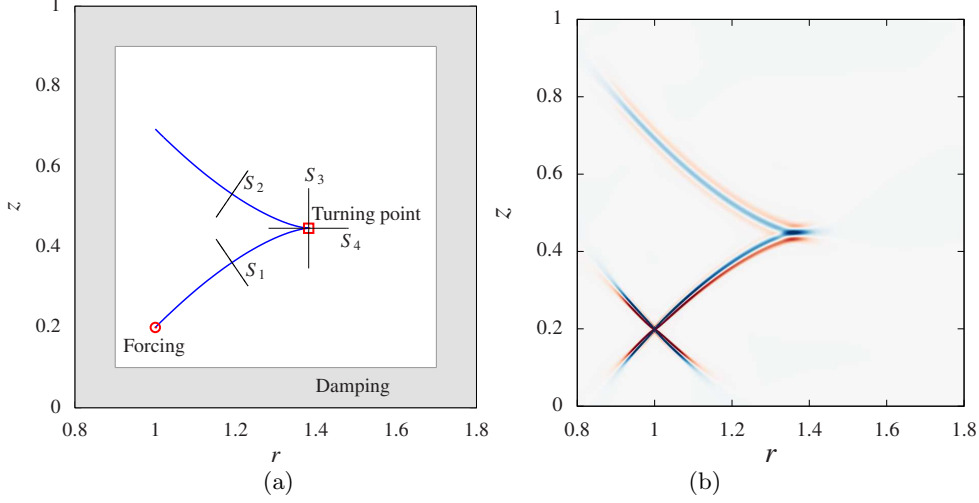


FIGURE 3. (a) Schematic of the numerical domain. The blue line shows the ray path from the forcing point (red circle) across the turning point (red square) and the ensuing reflected beam. Slices from S_1 to S_4 correspond to the locations where the comparisons between asymptotics and numerics are performed. The gray area is the damping region necessary to prevent reflections on the boundaries. (b) Transverse velocity U_ϕ once the harmonic response is reached for $E = 10^{-7}$. A movie showing the time evolution of the global solution and the rescaled local solution can be found in Supplemental materials.

$-\tilde{x}_\perp$ and include a phase shift of $-\epsilon_2\pi/2$. Note that the sign of this phase shift is given by the sign of $N^2 + \xi^2 - 2\varpi^2$ at the turning point. For a non-stratified fluid $\varpi = \xi_c$ and for a non-rotating or irrotational flow, $\varpi = N_c$. In both cases, this sign is negative ($\epsilon_2 = 1$), so the phase shift is $-\pi/2$.

5. Comparison with numerical simulations

In this section, we compare the asymptotic predictions of the previous sections with numerical simulations of the linear viscous problem. We consider a non-stratified fluid ($N = 0$) that is rotating with a non-uniform angular velocity profile $\Omega(r)$. As in the theoretical analysis, the problem is assumed to be axisymmetric about the rotation axis, and we use cylindrical coordinates (r, z) . We focus on the wave dynamics generated by localized forcing at a point (r_f, z_f) within a finite radial interval (r_i, r_o) distant from the axis (i.e. $r_i > 0$).

Instead of solving the harmonic perturbation equations (2.2), we solve the time-dependent linearized equations for the perturbations in the rotating frame with an external forcing term:

$$\frac{\partial \mathbf{U}}{\partial t} + 2\Omega(\hat{\mathbf{e}}_z \times \mathbf{U}) + r(\mathbf{U} \cdot \nabla \Omega)\hat{\mathbf{e}}_\phi = -\nabla P + E\nabla^2 \mathbf{U} + \mathbf{f} - \frac{\chi}{\tau}\mathbf{U}, \quad (5.1a)$$

$$\nabla \cdot \mathbf{U} = 0, \quad (5.1b)$$

where \mathbf{U} and P are the perturbation velocity and pressure, respectively. The radius r_f and the local rotation rate $\Omega(r_f)$ are used to non-dimensionalize the variables. The Ekman number is then defined as $E = \nu/(\Omega(r_f)r_f^2)$. Note that, as before, we have used the same notation Ω for both the dimensional and dimensionless rotation rates.

The external forcing \mathbf{f} in equation (5.1a) is prescribed as

$$\mathbf{f} = \sin(\varpi t) \exp(-(R/R_0)^2) \hat{\mathbf{e}}_\phi, \quad (5.2)$$

with $R = \sqrt{(r-1)^2 + (z-z_f)^2}$ is the distance from the forcing point located at $(1, z_f)$, and R_0 is the characteristic size of the forcing region. We choose R_0 small enough for the forcing to be considered nearly point-like, while still allowing the numerical resolution of the inner viscous structure of the fluid response around that point. Typically, we choose $R_0 = 10^{-3}$. Note that this forcing procedure does not give direct access to the structure of the emitted shear layer, in particular we cannot control the singularity strength given by the parameter m in equation (3.21). As shown below, our particular forcing procedure leads to a shear layer which is accurately modeled as a Moore and Saffman beam with $m = 2$.

Since we solve these equations in a finite square domain $[r_i, r_o] \times [z_i, z_o]$ with no-slip boundary conditions on all sides, we add the last term in equation (5.1a) in order to prevent reflections at the boundaries of the domain. This relaxation term ensures a fast decay of waves before they can reach and reflect on the boundaries. The function χ is zero in the bulk of the domain and reaches unity as soon as the distance from the walls is 10^{-1} or less, as indicated in gray in figure 3. The parameter τ is chosen to ensure a gradual absorption of the waves and minimise reflected waves, typically $\tau = 4$ (larger values lead to reflection from the damping layer itself while smaller values lead to waves reflecting from the boundaries).

In the following, we use the following set of parameters. The numerical domain is defined by $r_i = 0.8$ and $r_o = 1.8$ while the vertical extent is $z \in [0, 1]$. The forcing is centered at $(r_f, z_f) = (1, 0.2)$. The rotation rate of the fluid is non-uniform and varies linearly with the horizontal coordinate according to

$$\Omega(r) = 1 - \alpha(r - 1). \quad (5.3)$$

Note that this linear variation of the rotation rate is only valid away from the rotation axis. The differential rotation parameter α must be carefully chosen: it must ensure that a turning point lies within the computational domain, while also avoiding centrifugal instability. The latter condition is satisfied by requiring $\xi^2(r) > 0$ throughout the domain, where ξ is the epicyclic frequency defined in equation (2.4). For the linear rotation profile defined in equation (5.3), both constraints are satisfied over the radial domain $r \in [0.8, 1.8]$ with $\alpha = 1/2$. The Ekman number is fixed to $E = 10^{-7}$ and the wave frequency is set to $\varpi = \sqrt{3/2}$, so that the initial propagation angle at the forcing point is 45° . Finally, the remaining parameters are $R_0 = 10^{-3}$, which defines the size of the forcing region, and $\tau = 4$, which sets the damping timescale in the outer sponge layer to effectively suppress boundary reflections.

We solve this initial value problem using the open-source spectral element solver Nek5000 (Fischer, 1997; Deville *et al.*, 2002), which allows for local mesh refinement around the forcing region and the turning point. The domain is discretised using a number $\mathcal{E} = 10404$ of tetragonal elements while the velocity is discretised within each element using Lagrange polynomial interpolants of order 14. No dealiasing is used since the equations solved are effectively linear. Convergence has been tested by gradually increasing the polynomial order for a fixed number of elements. We focus on the time-harmonic solution obtained after the initial transient has decayed.

Our analysis focuses on the wave beam emitted from the source located at (r_f, z_f) , propagating toward the upper-right quadrant of the domain, see figure 3(a) and (b). The equation of the characteristic along which the beam is localized, is derived from (2.8) and takes the form

$$z'(r) = \frac{dz}{dr} = \frac{\sqrt{\Delta}}{\varpi^2} = \sqrt{5 - 5r + r^2}. \quad (5.4)$$

Integrating this expression yields the path of the characteristic

$$z(r) = \frac{3}{4} + \left(-\frac{5}{4} + \frac{r}{2}\right) \sqrt{5 - 5r + r^2} - \frac{5}{8} \log \left(5 - 2r - 2\sqrt{5 - 5r + r^2}\right) + z_f, \quad (5.5)$$

shown in blue in figure 3(a). The turning point is located at $r_c = (5 - \sqrt{5})/2$. For the present forcing, the structure of the beam is found to be well-described by a Moore-Saffman solution with singularity index $m = 2$. The evolution of this solution along the characteristic is described by equations (3.8), (3.16), (3.19), which lead to the following expression for the parallel velocity component:

$$u_{\parallel} \sim A \frac{C_0(r)}{|\tilde{x}_{\parallel}|^{2/3}} h_2(\eta) \quad , \quad \eta = \frac{F(r)x_{\perp}}{(E\tilde{x}_{\parallel})^{1/3}} \quad (5.6)$$

where

$$F(r) = \xi(r) = \varpi \sqrt{1 + z'^2(r)} = \sqrt{\frac{3}{2}} \sqrt{6 - 5r + r^2} \quad (5.7a)$$

$$C_0(r) = \frac{\sqrt{1 + z'^2(r)}}{\sqrt{r} z'(r)} = \frac{\sqrt{6 - 5r + r^2}}{\sqrt{r} (5 - 5r + r^2)^{1/4}}, \quad (5.7b)$$

$$\tilde{x}_{\parallel} = \varpi^2 \int_{x_{\parallel}^{(0)}}^{x_{\parallel}} \frac{(1 + z'^2(r))^{3/2}}{z'(r)} dx_{\parallel} + \tilde{x}_{\parallel}^{(0)} = \frac{3}{2} \int_1^r \frac{(6 - 5r + r^2)^2}{\sqrt{5 - 5r + r^2}} dr + \tilde{x}_{\parallel}^{(0)}. \quad (5.7c)$$

The azimuthal velocity u_{ϕ} is related to u_{\parallel} via equation (3.3a):

$$u_{\phi} = -iC_1(r)u_{\parallel}, \quad (5.8)$$

with

$$C_1(r) = \frac{\omega(r)}{\varpi \sqrt{1 + z'^2}} = \sqrt{\frac{3}{2}} \frac{(2 - r)}{\sqrt{6 - 5r + r^2}}. \quad (5.9)$$

The physical azimuthal velocity is then given by

$$U_{\phi}(t) = 2|A| \frac{C_0(r)C_1(r)}{|\tilde{x}_{\parallel}|^{2/3}} \Re \left(h_2(\eta) e^{-i(\varpi t - \phi_A + \pi/2)} \right). \quad (5.10)$$

If we consider the quantity defined by

$$U = \sqrt{U_{\phi}^2(t) + U_{\phi}^2(t + \pi/(2\varpi))} = 2|A| \frac{C_0C_1}{|\tilde{x}_{\parallel}|^{2/3}} |h_2(\eta)|, \quad (5.11)$$

we obtain a function that does not depend on time anymore. For each r , its maximum is reached on the characteristic curve $z = z(r)$ (corresponding to $\eta = 0$) and is given by

$$U_{\max}(r) = 2|h_2(0)| |A| C_0(r) C_1(r) / |\tilde{x}_{\parallel}(r)|^{2/3}. \quad (5.12)$$

This expression can be used to estimate the parameters $|A|$ and $\tilde{x}_{\parallel}^{(0)}$ in (5.7c). The best fit for r between 1.05 and 1.3 is obtained for $|A| \approx 0.0125$ and $\tilde{x}_{\parallel}^{(0)} = 0.010$, as illustrated in figure 4. Albeit a phase factor, the solution is then fully determined.

When the beam reaches the turning point, the approximation (4.20) with $m = 2$ has to be used:

$$u_{\parallel} \sim AC_t V_2(Y_{\parallel}, Y_{\perp}). \quad (5.13)$$

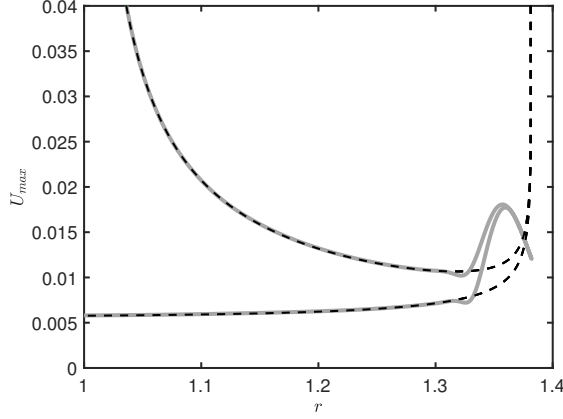


FIGURE 4. Plot of the numerical signal $\left(\sqrt{U_\theta^2(t) + U_\theta^2(t + \pi/(2\varpi))}\right)$ on the characteristic $z = z(r)$ (grey line), together with $U_{\max}(r)$ (black dashed line) given by (5.12) for $|A| = 0.0125$ and $\hat{x}_\parallel^{(0)} = 0.01$. Both incident and reflected beams are shown. The solid curves depart from the dashed curves upon entering the turning-point region.

The amplitude C_t , and local variables Y_\parallel and Y_\perp , are defined in this case by:

$$C_t = -\frac{4\sqrt{\pi}(3/2)^{7/12}}{5^{1/12}\sqrt{3(5-\sqrt{5})}} \frac{e^{i\pi/4}}{\hat{x}_{\parallel c}^{13/18} E^{1/18}} \approx -2.7276 \frac{e^{i\pi/4}}{\hat{x}_{\parallel c}^{13/18} E^{1/18}}, \quad (5.14a)$$

$$Y_\parallel = \frac{5^{1/6}(3/2)^{1/3}(r-r_c)}{|\hat{x}_{\parallel c}|^{2/9} E^{2/9}}, \quad (5.14b)$$

$$Y_\perp = \frac{(3/2)^{1/2}(z-z_c)}{|\hat{x}_{\parallel c}|^{1/3} E^{1/3}}. \quad (5.14c)$$

The physical azimuthal velocity near the turning point is then given by:

$$U_\phi(t) = 2|A||C_t|C_1(r_t)\Re\left(V_2(Y_\parallel, Y_\perp)e^{-i(\varpi t - \phi_A - 3\pi/4)}\right). \quad (5.15)$$

The reflected beam has a similar expression to the incident beam, but we have to change x_\perp in $-x_\perp$ and add a phase shift of $-\pi/2$. Moreover, the relation between u_\parallel and u_ϕ is now $u_\phi = iC_1 u_\parallel$, so we obtain

$$U_{\phi R}(t) = 2|A|\frac{C_0(r)C_1(r)}{|\hat{x}_\parallel|^{2/3}}\Re\left(h_2(-\eta)e^{-i(\varpi t - \phi_A)}\right). \quad (5.16)$$

The functions C_0 and C_1 remain unchanged for the reflected beam. However, the coordinate \hat{x}_\parallel differs, and is now given by:

$$\tilde{x}_\parallel = \frac{3}{2} \int_r^{r_c} \frac{(6-5r+r^2)^2}{\sqrt{5-5r+r^2}} dr + \hat{x}_{\parallel c} + \hat{x}_\parallel^{(0)}. \quad (5.17)$$

where

$$\hat{x}_{\parallel c} = \frac{3}{2} \int_1^{r_c} \frac{(6-5r+r^2)^2}{\sqrt{5-5r+r^2}} dr \approx 1.7663. \quad (5.18)$$

In figure 4, we see that the amplitude of the reflected beam along the characteristic is perfectly described by the quantity $U_{\max}(r)$ in (5.12), using the values of $|A|$ and $\hat{x}_\parallel^{(0)}$ estimated for the incident beam.

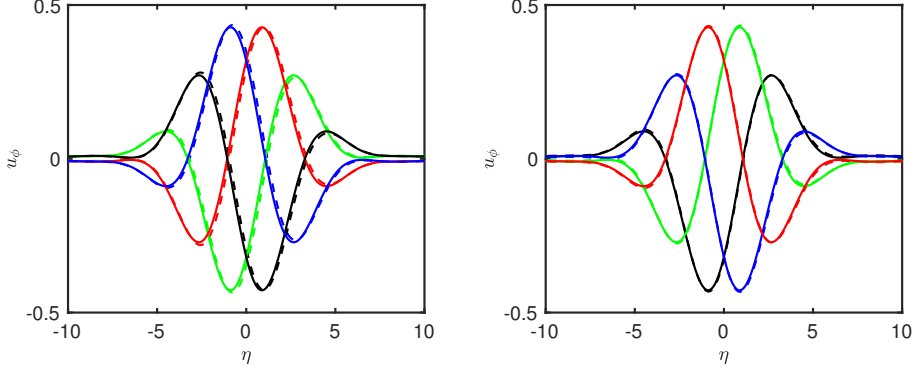


FIGURE 5. Structure of incident and reflected beams. Plot of $U_\phi(t_N)$, $N = 0, 1, 2, 3$ normalized by $M = 2|A|C_0C_1/(\tilde{x}_\parallel)^{2/3}$, as a function of the rescaled transverse variable $\eta = \tilde{x}_\perp/(E\tilde{x}_\parallel)^{1/3}$, in section S_1 for the incident beam (a), in section S_2 for the reflected beam (b), as shown in figure 3(a). The solid lines represent the theoretical solutions, while the dashed lines correspond to the numerical results. The colors indicate different times: $t = t_0$ (blue), $t = t_1$ (red), $t = t_2$ (green) and $t = t_3$ (black). In these plots, $|A| = 0.0125$ and $\tilde{x}_\parallel^{(0)} = 0.01$.

For the comparison of the beam transverse structure, we select four distinct times $t_N = t_o + N\pi/(2\varpi)$, $N = 0, 1, 2, 3$ spanning one oscillation period. The reference time t_o and phase ϕ_A are chosen such that

$$\max_{r_1 < r < r_2, z = z_c} |U_\phi(t_o)|$$

is the smallest together with the condition that $U_\phi(t_1) > 0$ at the turning point. Theoretically, the first condition is satisfied if $e^{-i(\varpi t_o - \phi_A - 3\pi/4)} = \pm i$ since $V_2(Y_\parallel, 0)$ is real for all Y_\parallel . The second condition implies that the positive sign must be chosen, which determines the phase as $\varpi t_o - \phi_A = \pi/4$. The solution is now fully specified for all time.

Figure 5 compares the numerical results with the theoretical solution for both incident and reflected beams. We observe very good agreement at all four times t_N . The reflected beams curves display the expected phase shift: the structure of the reflected beam at time t_N corresponds to the one of the incident beam at time t_{N-1} .

The solution in the turning point region is shown in figure 6 in both a vertical section (a) and a horizontal section (b) (sections S_3 and S_4 shown in figure 3(a)). Again, we observe good agreement between the numerical solution and the theoretical prediction. Note however, that the numerical solution in the horizontal section does not vanish for $t = t_0$ and $t = t_2$, in contrast to the theoretical solution. Capturing this variation would require incorporating higher-order corrections into the theoretical model.

6. Conclusion

In this work, we have shown that concentrated viscous wave beams can still be described by the solution introduced by Moore & Saffman (1969), even when the fluid is non-uniformly rotating and non-uniformly stratified. The wave beam follows the ray path obtained from the equation of characteristics, but its properties vary with the local conditions of the fluid. Explicit expressions for the beam width and amplitude have been derived by solving the governing equations in a reference frame attached to the characteristic. These results extend the analysis of Kistovich & Chashechkin (1998) that was limited to cases with an homogeneous direction, leading to a separable problem. Our

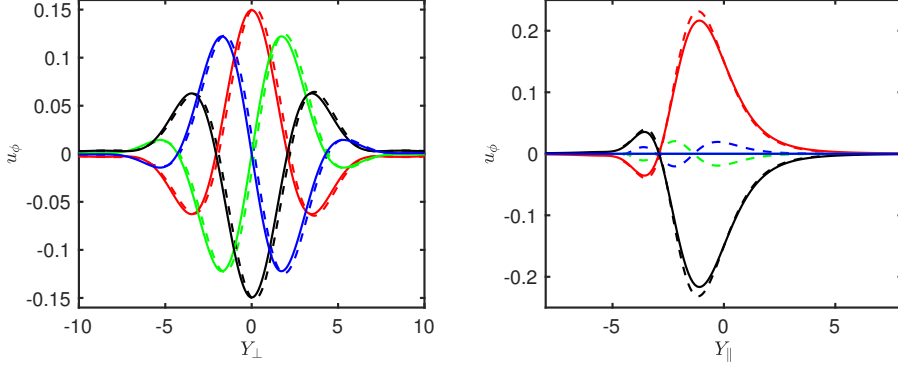


FIGURE 6. Structure of the solution in the turning point region. Plot of $U_\phi(t_N)$, $N = 0, 1, 2, 3$ normalized by $2|A|C_t C_1(r_t)$ in the vertical section S_3 (a) as a function of Y_\perp and in the horizontal section S_4 (b) as a function of Y_\parallel , see figure 3(a). As in figure 5, the solid lines represent the theoretical solutions and the dashed lines the numerical results. The colors correspond to the same times as before: $t = t_0$ (blue), $t = t_1$ (red), $t = t_2$ (green) and $t = t_3$ (black). The parameters $|A| = 0.0125$ and $\tilde{x}_\parallel^{(0)} = 0.01$ are also the same as in figure 5.

approach remains valid in the general non-homogeneous case. When the characteristic reaches a turning point, the amplitude diverges. To describe the wave beam in the neighbourhood of this point, a new asymptotic solution has been derived, which, as expected, takes the form of Airy functions. Matching this local solution with the incident wave beam allows us to fully describe the local behavior and demonstrates that a reflected beam is generated with the same structure as the incident beam. However, the reflected beam has experienced a $\pm\pi/2$ phase shift relative to the incident beam. The sign of the phase shift for the u_\parallel component is determined by the sign of the quantity $N^2 + \xi^2 - 2\varpi^2$ evaluated at the turning point. In the cases of a non-stratified or non-rotating fluid, this sign is always negative so the phase shift is $-\pi/2$. These results have been validated by direct numerical simulation for a non-uniformly rotating case.

It is important to note that the effect of reflection at a turning point on the viscous beam is very similar to the effect of a reflection at the rotation axis. In both cases, the viscous beam acquires a $\pm\pi/2$ phase shift but undergoes no contraction or expansion. This contrasts with reflections at inclined boundaries, where viscous beams are expected to either contract or expand depending on the boundary inclination angle during reflection, but without gaining any phase shift. However, the sign of the phase shift on the axis depends on another quantity: for the u_\parallel component, it is determined by the sign of $N^2 - \xi^2$ (see, for instance He *et al.*, 2022).

These findings could be useful to extend results obtained for a uniformly rotating fluid in a bounded domain. In He *et al.* (2022, 2023, 2025), it was shown that an asymptotic solution can be constructed for a uniformly rotating fluid in a spherical shell geometry by propagating viscous wave beams generated at critical points on the inner core. Two scenarios were considered in this bounded domain: (1) when the ray paths form a periodic circuit, and (2) when they converge towards attractors. In the first case, it was shown that the sum formed by the superposition of the infinitely many contributions from the critical point beam traveling along the periodic circuit is finite, provided there is a phase shift along the circuit. In the second case, the situation was reverse: an asymptotic solution close to the attractor was derived, but only if no phase shift occurs along the attractor. In a non-uniformly rotating medium, similar results may be expected. Suppose

the ray path emitted from a singularity (a critical point or a corner) generates a periodic circuit as it reflects on boundaries, axes and turning points. The viscous beam created by the singularity will travel on the same path indefinitely. As for the uniformly rotating case, a finite solution arises only if the sum of all contributions converges. This requires a net phase shift along the periodic circuit, which depends on the cumulative phase shifts acquired at each reflection, at turning points or axes. A similar argument applies to attractors. However, for the theory developed in He *et al.* (2023, 2025) to hold, the total phase shift around the circuit must vanish. This situation can occur, for example, when there are four reflections at turning points along the attractor, a configuration observed in figure 6(c) of Mirouh *et al.* (2016).

The present analysis has focused exclusively on linear aspects. Nonlinear effects on concentrated wave beams were investigated by Tabaei & Akylas (2003) who showed that Moore & Saffman similarity solution remains valid up to $O(1)$ amplitudes in uniformly stratified, non-rotating fluids. We suspect that this property may also hold in a non-uniformly stratified and rotating medium, provided that the beam remains sufficiently far from turning points, boundaries and the axis. Close to a boundary, Le Dizès (2020) and Chang *et al.* (2026) demonstrated that nonlinear effects become significant: an incident concentrated beam of amplitude ε interacts nonlinearly with the reflected beam, generating both a second harmonic and mean-flow correction of order $\varepsilon^2 E^{-1/3}$. This interaction prevents ε from reaching $O(1)$ values. This interaction is even stronger close to the axis, owing to the geometric focusing of the beam at this location (Le Dizès, 2015; Chang *et al.*, 2026). Near the turning point, the beam amplitude increases by a factor $E^{-1/18}$ and the incident and reflected beams interact. We therefore also expect significant nonlinear effects in this region.

The concentrated wave beam considered here may also become unstable. Fan & Akylas (2020) presented experimental and numerical evidence that, in uniformly stratified, non-rotating fluid, a propagating concentrated beam becomes unstable above a certain threshold amplitude. In their work, the beam width was not set by a viscous scale. It would therefore be useful to determine whether their results also hold in the viscous regime considered here.

Centre de Calcul Intensif d’Aix-Marseille is acknowledged for granting access to its high performance computing resources. This work was granted access to the HPC resources of IDRIS under the allocation 2025-A0180407543 made by GENCI.

Declaration of Interests. The authors report no conflict of interest.

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